

	community	of UK rese	of global rese	ge of UK re	frequent words in titles
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15	15	163	194	84	research integrity research integrity world proc
32	32	93	113	82.3	algorithmic data accountability human decisio
7	7	182	261	69.7	robot autonomous robots verification human s
13	13	121	226	53.5	autonomous control vehicles based vehicle aut
12	12	97	231	42	robot soft based control robots model robotic
8	8	95	259	36.7	uav networks based allocation resource wireles
22	22	48	149	32.2	robot control based robots robotic locomotior
11	11	61	246	24.8	based networks uav data trust multi learning m
28	28	21	120	17.5	based design systems mobile control robot dat
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10	10	34	249	13.7	control based robot multi robotic cooperative
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3	3	34	300	11.3	learning robot based robotic deep human cont
16	16	19	193	9.8	control multi based systems robot agent multi
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6	6	18	272	6.6	control multi systems agent multi agent agent s
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27	27	6	124	4.8	diabetes control loop closed closed loop type t
2	2	14	325	4.3	robot control based planning autonomous veh
18	18	7	169	4.1	based planning aerial control learning robots ar
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19	19	4	164	2.4	robot control based humanoid design research
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31	31	1	114	0.9	agent multi systems multi agent control agent s
26	26	1	129	0.8	trust autonomous driving human control autoi

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2	2	24	44	5	0	3	618
3	3	9	99	1	0	5	399
4	4	19	54	2	0	0	534
5	5	1	129	8	0	1	418
6	6	4	37	0	0	1	583
7	7	10	118	5	2	4	336
8	8	9	192	3	1	1	254
9	9	27	88	3	0	0	365
10	10	20	57	4	0	0	380
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12	12	7	57	2	0	1	305
13	13	73	61	11	0	3	261
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15	15	0	87	27	18	0	0
16	16	14	48	0	0	2	411
17	17	10	166	2	3	18	87
18	18	6	19	0	1	0	303
19	19	1	9	0	0	0	264
20	20	3	43	2	0	1	306
21	21	7	18	0	0	1	321
22	22	0	22	3	0	0	254
23	23	2	77	1	1	1	181
24	24	6	12	0	0	0	260
25	25	4	112	0	1	3	122
26	26	18	54	2	0	5	113
27	27	0	90	0	1	1	20
28	28	2	93	1	1	2	118
29	29	2	103	1	0	0	112
30	30	5	122	1	5	0	82
31	31	2	25	0	1	1	248
32	32	4	120	40	2	3	39

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0	1	73	621	99 -	-	-	
1	2	32	555	155 -	-	-	
2	18	13	278	60 -	-	-	
3	19	8	211	70 -	-	-	
4	21	15	275	82 -	-	-	
5	24 -		212	70	12 -	-	
6	26 -		118	24 -	-		28
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9	31	34	197	80 -	-	-	

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0		1	451	Target-Driven Visual Navigation in Indoor Scenes Using Deep Reinforcement Learning
1		1	288	Reluplex: An Efficient SMT Solver for Verifying Deep Neural Networks
2		1	174	SqueezeSeg: Convolutional Neural Nets with Recurrent CRFs for Semantic Segmentation
3		1	161	Team IHMC's Lessons Learned from the DARPA Robotics Challenge
4		1	147	SoPhie: An Attentive GAN for Predicting Paths Compliant to Human-Like Behavior
5		1	139	WaterGAN: Unsupervised Generative Network to Enable Realistic Image-to-Image Translation
6		1	117	Secure State Estimation for Cyber-Physical Systems Under Sensor Denial
7		1	108	Design of a Momentum-Based Control Framework and Application to a Quadrotor
8		1	100	A Learning-Based Framework for Velocity Control in Autonomous Navigation
9		1	98	Dynamics and trajectory optimization for a soft spatial fluidic robot
10		2	189	End-to-End Driving Via Conditional Imitation Learning
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12		2	152	Learning agile and dynamic motor skills for legged robots
13		2	112	Self-Organization as a Supporting Paradigm for Military UAV Operations
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33		19	63	Gait adaptation to visual kinematic perturbations using a reinforcement learning approach
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45		21	51	Integral Line-of-Sight Guidance for Path Following Control of Underactuated Systems
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93	31	169 \href{https://doi.org/10.1109/9319100.2020.9211111} Secure and Trustable Electronic Medical Records Sharing using Blockchain
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Advances, and Opportunities

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nsor-Augmented Pump with Low-Glucose Suspend Function: A Randomized Crossover Study

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ty, and the T1D Exchange

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94	31	\href{https://doi.org/10.1002/anie.198900000}	Li-Hua Xie	Nanyang Te	25	924	1989
95	31	\href{https://doi.org/10.1002/anie.200400000}	Guoqiang Hu	Nanyang Te	19	231	2004
96	31	\href{https://doi.org/10.1002/anie.200600000}	Hong-Yong Yang	Ludong Uni	19	100	2006
97	31	\href{https://doi.org/10.1002/anie.199000000}	Ben-Mei Chen	Chinese Un	15	420	1990
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