



TAS Conversations Transcript

Episode 1: Autonomous Vehicles

Recorded on 28 July 2021

Hosted by Sean Riley

Featuring: Siddhartha Khastgir, Professor Sarah Sharples, Dr Jo-Ann Pattinson, Professor Mohammad Mousavi, and Dr Jack Stilgoe.

Transcript begins

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Welcome to this the first of our TAS Hub
conversations the Trustworthy Autonomous Systems

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Hub is here to establish a platform for the UK to
deliver best practices for design regulation and

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operation of autonomous systems which are there to
benefit society. The idea is that we build systems

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that are trustworthy in principle and also trusted
in practice. For this first fireside chat note the

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air quotes albeit socially or more importantly
physically distanced we are looking at AVs or

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autonomous vehicles perhaps if we get an AV we might be able to meet each other who knows now

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the TAS podcast living with AI has talked a couple of times about AVs and we've gathered a diverse

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group of experts to chat about it today and before we get into the meat of it you can get all sorts

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of information about the TAS Hub events, podcasts and how to get involved at our website task.ac.uk.

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So on to the main event first I'd like to welcome all our guests and we'll get them to introduce

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themselves and for no other reason than it's how I've typed it here first name alphabetical order

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let's start with Jack. Hi everybody I'm Jack Stilgoe, I'm associate professor in science

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technology studies at University College London and I run a social science research project



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that's called Driverless Futures that's all about
how we make good policy for autonomous vehicles.

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My name is Jo Pattinson and I'm a research
fellow at the Institute for Transport Studies

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at the University of Leeds and I'm a
Legal Research Fellow so I investigate

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legal issues to do with autonomous
vehicles. I'm also a solicitor

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I'm a consultant at Addulshaw Goddard
solicitors in their transport team.

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I'm Mohammad Mousavi, Professor of Software
Engineering about to join King's College London,

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probably by the time this is broadcast
I will be at King's College London

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my area of interest is in validation and verification of autonomous systems and I lead

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also the Verifiability Node in the TAS programme.

Hi Sean, hi everybody, Siddhartha Kastgir Head

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of Verification and Validation for connected autonomous vehicles at WMG,

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the University of Warwick. I'm on a mission of making autonomous vehicles safe but also

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ensuring they're deployed in a safe manner. I do a lot of work on the standard side of things

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ensuring that the industry as a whole agrees to strong standards that we have to adhere to.

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Hi everyone I'm Sarah I'm a Professor in Human Factors at the University of Nottingham and one

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of the investigators on the TAS Hub where I take a lead on equality, diversity and inclusion. I'm



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currently a pro-vice-chancellor at the University of Nottingham but by the time this is broadcast

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I will be chief Scientific Advisor for the Department for Transport and obviously in

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that role responsible for making sure that we have the right research ecosystem to inform transport

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policy but also taking the understanding that we have from academic research and ensuring that that

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informs transport policy in the most effective way and speaking here in a personal capacity.

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Fantastic, and so if I can start with you actually because the thing I wondered

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initially I was going to say so what are you going to be telling the government about

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AVs but I was going to just sort of say
can we draw on something you've worked on

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in the past so I know you've been involved
in Network Rail and doing things to do with

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the railways, did they ever
consider autonomous trains?

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Yes I mean it's worth remembering that we've
almost had autonomous trains since the 1960s

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so many of you may or may not be aware that
the Victoria line was one of the pioneers

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in terms of autonomous vehicles and it uses
now it's it's been modified in recent years

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a system where the spacing of the vehicles is
managed from an autonomous an automated system,

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of course, the driver still has an important role
in that context but the driver is much more about



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making sure that they provide that really important link between the automated vehicle

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and the passengers themselves but if you ever get a chance to go and visit the Victoria line control

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system it's a really really interesting space to explore because actually we'll see that the

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majority of the decisions particularly about the routing and the spacing and the frequency of the

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trains happens on an automated basis and in fact it's pretty much been doing so since the 1960s.

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We're living in an age of automated vehicles already.

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Has anyone got anything they particularly want to say before I start directing because I mean

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we've got liability issues and we've got Jo
there who hopefully can talk to us about those,

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we've got sort of the trust issues and
and there are all sorts of you can talk

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to us about that from a social point of
view, from a technical point of view.

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Yeah I definitely agree with everything that Sarah
said that we have a history a very rich history of

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research in designing and engineering
autonomous systems. I think what is

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changing right now is that we are entering an era
where autonomous systems will interact with lots

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of human and non-autonomous systems and they
have to make themselves understood, negotiate

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their way and then this is something that is
somewhat unprecedented to what we have had



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in the past. So future AVs will have to talk to
and communicate to human beings to human drivers

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to other road users and this is a very
very interesting challenge ahead of us.

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And socially, I'm going to come to Jack with this
one because you know that idea of communicating

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with a robot, I mean, we do this all the time
you know we've all become accustomed to saying

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I'm not going to mention any of the virtual
assistants by name in case it sets somebody's

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device off but hey 'blah' you know what's the
next train to London? or whatever is that going

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to be a similar kind of thing, are we just going
to get used to you know asking the vehicle to

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take us where we want or the vehicle is going
to tell us that we're in the way or whatever,

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how's that going to work socially are
going to people going to accept that?

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That's the right way of thinking about it Sean
is to ask well how are we going to get used to

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this right because the the the sort of ideal of
artificial intelligence is that it's a technology

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that can adapt and learn human capacities and then
emulate those and then and then supersede them

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and what will happen certainly with with
autonomous vehicles is that there will be you know

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the technology adapting to society and learning
how to fit in in effect learning how to drive

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but also there will be a huge amount of
society learning to adapt to the technology



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and that's a bit of a dirty secret among among the engineers right they don't want to talk about that

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because they don't want to be seen to be making impositions upon people saying you know you might

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learn how they might have to learn how these things behave so that you you learn to cross the

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road differently or you learn to drive differently around these these technologies when you're when

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you're in mixed traffic so it's going to be a negotiation that trust relationship and at the

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moment we're hearing more of the sort of utopian techno side of that of that conversation than the

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rather more complicated messy side which is how does the society learn to deal with these things.

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And the often the thing that's brought up with anything to do with AVs is all the edge cases

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but actually just the general day-to-day is going to be really interesting but the thing that we can

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never get away from and we've got to discuss it is this kind of liability issue what happens if

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you know from accidents to mistakes taking you to the wrong place all sorts of things like that

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you know we live in an ever-increasing litigious society Jo how are we going to

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manage this kind of idea of let's be honest whose fault is it where is the blame lie?

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Yeah well I guess there's two on this topic I guess there's two things that I'm particularly

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interested in, one is that the way that the framework that we're that looks as though we're



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currently setting up at the UN level and at a UK level is that especially where you're looking at

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having a a driver that is sharing responsibility with an AV is that we it looks as though we

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are potentially going to be legislating behavior on the heart of the driver that might not actually

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be physiologically possible on the part of the driver as in here I'm talking specifically about

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responding to transfer demands transfer of driving demands from system to driver

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and everyone who works in this space knows that the drivers don't necessarily do that very well

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but as when you as Jack pointed out their the public is necessarily aware of that

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they're not aware of their own physiological and cognitive limitations that may prevent them from

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responding with the best will in the world drivers may not respond in the way that they're meant to

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and they will end up there will be liability issues for them despite all their best intentions

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in sharing responsibility with the vehicle and the other issue which I'm particularly interested

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in is the types of data and how are they how the types of data that is going to be recorded about

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all this and who has access to that data what type of format that data is going to be given to people

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because that is extremely relevant in terms of an insurance investigation in terms of a criminal

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investigation, civil liability are you going to get a spreadsheet that simply says yes you did a



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break input for example or do you have access to
the data behind that behind that data so these

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are the types of very gritty issues which
we still haven't gotten to the bottom of.

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Yeah this is the kind of the idea of the machine
beeping or whatever the notification is to say

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hey you've got to take control now and how much
warning you're going to get for that and what

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sort of you know state is going to put the driver
in there's another side issue to this which is

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you know whenever we talk about technology
and things become more computerized we have

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to worry about the possibility of being
hacked and various things like that is

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that something one of you would like to sort of take on is that Siddhartha or Mohammed from a

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technical point of view how do we guard against say you know hacks or whatever?

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If we try and stop hacking from happening that's not going to happen there will always be a clever

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person in the society who will find out a way of penetrating the system what we as engineers or

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as as designers of systems need to do is identify that we are being hacked and then go into a safe

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mode it's not about preventing the hacking from initially taking place it's about identifying that

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something is going happening so if we take that mindset into picture I think that's that's would

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be a kind of a departure from the way we tend to look at cyber security we tend to ensure that



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the system is secure but that's actually kind of
oxymoron you cannot prevent somebody from creating

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a append text on your system so it's about trying
to detect and then doing the subsequent activities

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just accepting that these are going to be things
that happen and making sure that we manage them

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yeah it's it's uh makes sense I mean there are
safety and security concerns across the board

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with this so I mentioned hacking we've obviously
mentioned kind of the the blame or the the legal

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side of things but the point is as well is that
there's always potentially going to be a glitch

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maybe it's in an edge case maybe it's something
nobody's thought of maybe it's you know what's

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the safe mode here how you mention safe mode
for hacking is that just well the vehicle comes

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to a gentle stop and you know hopefully in a safe
place what what's the what's the way around this?

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Let's first give an engineering viewpoint on this
and then I'll give you the right viewpoint on this

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uh the engineering viewpoint on this is to
make the system come to a standstill that's an

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engineering viewpoint on this but if you consider
the kind of interactions the autonomous vehicles

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or autonomous systems are going to have we
need to have a departure from the way we

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treat safety we tend to think of safety as just
that vehicle needs to be safe and because now

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the vehicle is in a wider system we need to have
this systems approach where society and public and



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humans are also part of that system so safety needs to be taken at a much higher abstraction

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level than just at that vehicle level so I think so that would be the right answer I'm not sure

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that we've got to it right now but that's the journey that we as a society need to uh take.

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There's also a there's a cost implication here isn't it I mean we've seen commitments from

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various governments to switching from fossil fuels and and looking if you take a sort of look at the

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market now and just decide right I'm going to move to an electric vehicle there's a huge price sort

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of bump in moving over to that if we also take into account the technology that will be required

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to make autonomous vehicles work it's going to be costly isn't it is it going to be expensive?

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I think this is another another one of those issues where where the hype and the reality

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are currently wildly far apart right I think so the story that's currently being told you know

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if you would listen if you were to listen to what say Elon Musk would say about autonomous vehicles

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it's about in effect a like for like replacement you take a conventional car off the road you put

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an autonomous vehicle in its place it learns how to drive and basically nothing else in the

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world needs to change I think we have to realize that the whole system of vehicles roads mobility

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you know we do need to see that as as a whole and that throughout history when there has been a new



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technology arriving the system the infrastructure
has to adjust as well in order to make that

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technology work and in order for it to to work
safely and it will happen with autonomous vehicles

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as well we can imagine you know small incremental
changes to things like traffic lights to mean that

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they communicate their status electronically
rather than a camera having to look at the

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color of a traffic light which is a rather absurd
thing for to imagine in in engineering terms but

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also we could look at you know the redesign
of roads that maybe suit autonomous vehicles

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slightly better than they suit conventionally
driven vehicles we might look at the redesign of

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of our lives to mean that pedestrians are no longer allowed to go on certain forms of roads in

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the same way as they know that they're currently not allowed to go on motorways and things so

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if you see this as a as one big what a social scientist would call a socio-technical system

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the engineering challenge looks vast right how we get from here to there looks extremely complicated

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it's going to be a mix of sort of incremental changes and some pretty radical disruptions.

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But one of those changes that is mooted occasionally and it seems to make perfect sense

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to me is this idea of sharing vehicles because you know I have a car parked outside maybe once

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or twice a week I need to drive somewhere and film something with my video camera and the rest time



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it's sitting there there might be 10 cars on our street and and half of them are there nearly all

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the time you know they might not be the same ones but why not have this idea of you know

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when you need an estate car because you're going to Ikea the estate car is the one you take

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it's not it doesn't belong to the guys at number four it might just be a pool car I don't know

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so is that something that's been seriously considered across the board?

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Absolutely and I think one of the things that's worth us remembering is the spectrum

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of what we mean by autonomous vehicles so first of all as as Jack's sort of implied actually what

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we're probably not going to have is a big bang switch we're going to have gradual incremental

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addition of autonomy and automated technologies in the vehicles that we already have but we're

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also going to see this shifting mindset so as Jack was talking about in terms of the socio-technical

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challenge of the what a future transport system might look like let's remember that some of the

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best use cases for autonomous vehicles aren't necessarily a conventional family car that you

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talked about here it's how do we get from the car park to the airport in an an airport context

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it's looking at last mile delivery of goods it's looking at particular types of cities or types of

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rural locations that might particularly benefit from autonomy and and it's also interesting that



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you talk about the sort of electric vehicles and other factors as well we've got lots of different

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things happening that are radically changing the way in which we move both as individuals

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and within our public transport and actually what we need to do is try and understand how all of

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this fits together because some of these things are going to be much much easier and quicker to

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shift and some of them will require that quite difficult mindset change that Jack referred to.

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We've discussed in a podcast before you know automated vehicles flying vehicles taking medical

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supplies to places and as you say you know this idea of that last-mile delivery you know we know

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Amazon are trialing whether it's successful or not drone deliveries whether it's practical or

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not as well might be another question but hey.

So one point that is relevant to the discussion

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both about liability and about safety and security and their connection I think it's the way we build

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systems so so we may as also pointed out by

Jack and Sarah we may need a different mindset

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in engineering these systems that takes human beings very seriously and also takes this whole

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interaction very seriously and one aspect that is definitely um not very prominent right now and

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should become much more prominent in the future is technical transparency of these systems so

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these systems evolve they learn that they

they change their behavior and if there is not



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sufficient technical transparency being built into these systems then finding the root cause for for

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various accidents becomes impossible and because these systems are becoming increasingly complex

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we need more transparency built into these systems in order to analyze how they behave

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and and also make the user and this divider society aware of of the consequences of

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that different behavior that also relates to the aspects like ethics right so the the user should

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be aware of the type of ethics that is implemented in the car and if that that is modified the user

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should also be aware of those modifications so I think technical transparency is something that is

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a bit overlooked and and should become much more prominent in the agenda of building these systems,

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And even with some of the complicated edge cases in the engineering side of things the ethics is

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of I would say more difficult problem to solve than than even any of the the technical side of it

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we've talked about it being a sort of slow change over into it it won't be an on off switch

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so there's going to be all sorts of integration issues with human drivers working with

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autonomous vehicles in the same mix as well as in different kind of areas

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you know whether it be drones or whatever but are we going to have a huge kind of

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pardon the kind of cliché rise of the robot style unemployment problem Sarah?



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If you've ever heard me speak before then I've probably mentioned my favourite ever academic paper

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which was called ironies of automation and it was published in 1983

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and one of the ironies of automation that was highlighted was around the changing

0:19:42.560,0:19:48.000

nature of jobs as we introduce automation and the change of jobs from active jobs

0:19:48.000,0:19:53.680

active control jobs to passive monitoring jobs and the fact that those different skills might

0:19:53.680,0:19:59.840

be required and but actually we might end up with almost the the wrong skills being trained

0:19:59.840,0:20:05.200

in the people who are now doing the jobs because the automation itself has changed. When I think

0:20:05.200,0:20:10.320



about automation in all sorts of contexts whether
it's vehicles or manufacturing or other contexts

0:20:11.040,0:20:15.680

I try and think about what the changing
nature of skills requirements might be

0:20:16.240,0:20:22.480

and the changing nature of jobs so yes of course
we have a responsibility to make sure that any

0:20:22.480,0:20:29.440

sort of whole scale implementation of technology
doesn't radically shift the number of jobs that

0:20:29.440,0:20:33.280

are available from a sort of national point of
view because then we end up with all sorts of

0:20:33.280,0:20:38.560

unintended consequences but what's really helpful
for us to think about is the changing nature of

0:20:38.560,0:20:43.840

jobs that might come about through the nature
of automation it's worth remembering that in

0:20:43.840,0:20:51.840

the 1970s we all thought that by now in fact by
the 1990s we would be working four day weeks um



0:20:51.840,0:20:58.400

we would have all of our household tasks and many of our other tasks done by automated technologies

0:20:58.400,0:21:05.360

and actually what happened was those automated technologies came but our work tie our work lives

0:21:05.360,0:21:10.080

actually probably increased in terms of the number of hours we worked rather than decrease the number

0:21:10.080,0:21:14.960

of hours because as a society and there are others around who know much more about this than I do

0:21:14.960,0:21:21.120

as a society we changed and adapted so actually what's really important here I think is to think

0:21:21.120,0:21:27.200

about what the changing nature of jobs might be and the changing nature of roles might be

0:21:28.000,0:21:32.240

and make sure that the work that we're doing when we're looking at autonomous vehicles

0:21:32.240,0:21:37.120



is linked up with that wider societal questioning so that we can make sure

0:21:37.120,0:21:41.200

that we're informing those skills requirements in those skills debates in a responsible way.

0:21:41.840,0:21:46.560

And just on the subject of automation because I used to work in broadcast automation where the

0:21:46.560,0:21:52.160

idea was you came in and you took a gallery in a television station of five or ten people and

0:21:52.160,0:21:57.600

you switched it to be one person pressing one button and what actually happens is all of the

0:21:57.600,0:22:02.160

jobs that are being done in the gallery just have to be done at a different stage usually by typing

0:22:02.160,0:22:07.440

instructions into a computer but you can just end up moving where the decision making process

0:22:07.440,0:22:12.800

happens so that when you do press that one button lots of things happen that have been pre-decided



0:22:12.800,0:22:15.760

that actually you have now haven't got
much of a chance to change if you need to

0:22:16.480,0:22:19.440

so you become less dynamic,
Jack you wanted to speak.

0:22:19.440,0:22:25.040

Yeah just to follow what what Sarah was saying I
think she's absolutely right but you know I think

0:22:25.040,0:22:31.360

it's important to remember that the sort of the
history of technology employment and automation

0:22:31.360,0:22:37.600

you know is one in which automation does not
replace labour it sort of displaces and transforms

0:22:37.600,0:22:46.080

labour it reconfigures jobs jobs are not the same
things as as as tasks so what does that mean for

0:22:46.080,0:22:54.080

the road? well I mean it it could mean all sorts
of things but if you want to sort of un some of

0:22:54.080,0:23:00.480



the transformations that that might be created
in a world in which a lot of driving is automated

0:23:00.480,0:23:04.000

I think you can look at what's been happening
the last few years to do with the gig economy

0:23:04.560,0:23:11.920

right where it wasn't a robot saying I can drive
your goods from a to b it was a relatively small

0:23:11.920,0:23:17.200

technological uh invention but more a business
model innovation that has transformed the

0:23:17.200,0:23:22.640

nature of work yet which yes it's created some
flexibility but also it's created some enormous

0:23:22.640,0:23:28.800

downsides as well right and we so we shouldn't kid
ourselves that robots put people out of work right

0:23:28.800,0:23:35.120

people put people out of work and then create
different different jobs using the affordances

0:23:35.120,0:23:40.800

of robots so it's not going to be at all at all
straightforward to anticipate what's going to



0:23:40.800,0:23:46.560

happen to the future of of driving jobs and and
there is an interesting point there which is uh

0:23:46.560,0:23:50.880

which has been brought up before which is uh with
the amount of computation required a minute to

0:23:50.880,0:23:57.600

take a car somewhere for instance and safely it's
much cheaper to have a human sitting potentially

0:23:57.600,0:24:03.200

short term anyway uh Siddhartha I think you wanted
to say something yeah just to add to what Sarah

0:24:03.200,0:24:10.960

and Jack's point here um I think we should look
at it rather as an opportunity uh of leveraging

0:24:10.960,0:24:18.720

the benefits of automation while compensating for
what might be perceived as drawbacks so there's a

0:24:18.720,0:24:25.760

lot of work we as academics engineers policymakers
could do in terms of reskilling the workforce uh

0:24:25.760,0:24:31.840



to cater to the new types of jobs that would be created because automation has been introduced so

0:24:31.840,0:24:38.480

I would rather say that we are creating new jobs than uh losing jobs over here I think that focus

0:24:38.480,0:24:43.520

needs to be brought in in terms of reskilling you can look at it even as a as engineer so I am

0:24:43.520,0:24:48.960

a trained mechanical engineer but I'm not working on nuts and bolts right now I'm working on making

0:24:48.960,0:24:53.920

autonomous vehicles safer so there's a lot of transition I have had in my own career in the last

0:24:53.920,0:24:59.440

10 years from being a hardcore mechanical engineer to what I now call as a mechatronics person so i

0:24:59.440,0:25:06.480

think the same is true for the wider workforce non-engineering workforce uh also over here.

0:25:06.480,0:25:10.960

Yeah so I wanted to react to two points first of all I disagree that it's cheaper to have



0:25:10.960,0:25:15.680

a human driver in in the driver's seat in
many applications if you look at how much

0:25:15.680,0:25:24.160

for example an NVidia board costs right now uh if
you have a proper programming uh skill in place

0:25:24.960,0:25:30.880

and you can make it work and then you calculate
for how long that nvidia board will uh will go

0:25:30.880,0:25:35.760

for for an autonomous vehicle it's much cheaper
than a human driver for the same period so I think

0:25:35.760,0:25:42.320

the challenge is not um the cost of hardware and
and having an autonomous vehicle built I think the

0:25:42.320,0:25:46.880

challenge is to have the right skills to program
them and and make sure that they're safe if you

0:25:46.880,0:25:51.040

manage you may manage to do that it's likely to
be much cheaper in many applications then ...

0:25:51.040,0:25:54.880



The point was at the moment right now
put someone in a car quite cheap...

0:25:54.880,0:25:58.240

If you have the right software then
it's much cheaper to use the the

0:25:58.240,0:26:01.760

autonomous technology but anyway and the
second point I wanted to make is that

0:26:01.760,0:26:08.880

um we we learned from this all this automation
history that we need to be more agile

0:26:08.880,0:26:14.640

in terms of engineers in terms of educators
in terms of students and and be reactive to

0:26:14.640,0:26:19.920

all those changes in our surroundings so in
the past you could uh join a company and have

0:26:20.640,0:26:27.520

30 years of safe career just doing what you
did 30 years ago maybe but nowadays we should

0:26:27.520,0:26:32.160

be more more receptive of the changes around
us also us as academics we should be much more



0:26:32.160,0:26:38.000

receptive of things changing around us and reacting to that and that is something that

0:26:39.920,0:26:44.640

we should take into account also for example in designing curriculum which we should uh we should

0:26:44.640,0:26:48.480

look into what is happening and then design our curriculum accordingly every now and then.

0:26:49.040,0:26:53.920

And it's interesting mentioning kind of like reactive and agile and changing i

0:26:53.920,0:26:58.240

I want to bring Joe in on this because we've mentioned the podcast before how does the law

0:26:58.240,0:27:01.120

keep up with things that are changing so fast? and

0:27:01.760,0:27:06.160

you know it it's difficult isn't it to make laws about something that perhaps isn't there yet?

0:27:07.520,0:27:14.480

Yeah the laws it's never really been famous for



um being at the forefront of these things it

0:27:14.480,0:27:24.000

generally is playing catch-up um in terms of no
matter what aspect of or of autonomous vehicles

0:27:24.000,0:27:31.520

or or autonomous systems you happen to name um we
we're currently at an international level and a

0:27:31.520,0:27:39.200

national level there are regulations being drafted
and redrafted with the input of various um experts

0:27:40.080,0:27:49.380

and it is a constantly changing and updating uh
situation so and it really is um it's it really is

0:27:49.920,0:27:54.400

an adaptive form of regulation that that
we that we're involved in when it comes to

0:27:54.400,0:28:00.960

automation where we are literally learning as
we go along um but unfortunately in terms of

0:28:00.960,0:28:08.560

it is always going to be behind um and and that
is that is that is the nature uh unfortunately



0:28:08.560,0:28:15.840

of law that it it has to it has to look at
what it has to react to to what's happened so

0:28:15.840,0:28:17.520

Fair enough yeah go ahead Jack

0:28:17.520,0:28:21.360

It's quite an interesting question I know the
Siddhartha will have will have thoughts about this

0:28:21.360,0:28:25.600

as well so you can think about the relationship
between law and technology in a number of

0:28:25.600,0:28:28.720

different ways I think particularly interesting
when you're thinking about technologies that

0:28:28.720,0:28:36.560

purport to be able to drive right because one one
requirement could be here this technology has to

0:28:36.560,0:28:44.000

follow exactly the rules that a human driver needs
to follow in order to be certified to be released

0:28:44.000,0:28:49.520

onto the road right so we could actually say well
the law already exists the technology just needs



0:28:49.520,0:28:56.560

to follow the the law now that becomes complicated
in a few ways that Siddhartha can can can tell you

0:28:56.560,0:29:03.520

uh all about but it might lead to sub-optimal
social outcomes because maybe actually in order

0:29:03.520,0:29:08.560

to realize the potential of this technology we
need to change the law so and this so there's

0:29:08.560,0:29:14.240

this sort of dialogue between between the the law
and technology we're just saying a rule following

0:29:14.240,0:29:19.200

technology might not be the best for everybody
and might lead to some impossible situations.

0:29:19.200,0:29:23.120

I can just imagine one we mentioned
before about the kind of clumsy

0:29:23.120,0:29:27.360

camera looking at the traffic light working out
what color it is and deciding whether to go well

0:29:27.360,0:29:31.520



if the entire road was just autonomous
vehicles the traffic lights shouldn't be

0:29:31.520,0:29:37.760

required at all right because presumably the
the vehicles would communicate and negotiate

0:29:37.760,0:29:40.400

who goes where would is that am
i right with that Siddhartha?

0:29:41.600,0:29:47.760

Yeah yeah yeah you but that's a utopian world that
we're talking about and as Sarah and Jack said we

0:29:47.760,0:29:54.560

would be in a gradual shift towards this i'll give
you a very simple example where just following

0:29:54.560,0:30:01.120

the law as it is today is not the optimal
solution so imagine of a zebra crossing as as

0:30:01.120,0:30:05.840

human drivers if we approach a zebra crossing as
a pedestrian standing next to the zebra crossing

0:30:05.840,0:30:11.040

you're supposed to stop that's all what sane human
drivers would do imagine the same thing being



0:30:11.040,0:30:16.640

done by an autonomous vehicle so the autonomous vehicle stops at the zebra crossing as per the law

0:30:17.360,0:30:22.960

the law does not state how long should the autonomous vehicle stop if the pedestrian just

0:30:22.960,0:30:28.880

stands next to the zebra crossing chatting on the phone does the autonomous vehicle stop there in

0:30:28.880,0:30:35.520

indefinitely and cause you uh traffic jam behind itself so those are the kind of assumptions that

0:30:35.520,0:30:41.760

need to be taken into consideration when we sort of redraft the law or come up with the

0:30:41.760,0:30:49.760

the law of framework 2.0 for autonomous vehicles we keep on saying autonomous vehicles automation

0:30:49.760,0:30:56.560

is much safer than human drivers but we uh belittle how good human drivers are

0:30:56.560,0:31:00.640



there's a lot of implicit things that
we do that are not defined in anyway

0:31:01.360,0:31:07.840

which actually keep the world safe and those
will need to be defined in this in this new law

0:31:08.560,0:31:14.000

when we are planning of a safer society
considering all the actors it's very easy

0:31:14.000,0:31:19.360

to make autonomous vehicles safe it's difficult
to make a society with autonomous vehicles safe.

0:31:19.360,0:31:20.080

Sarah,

0:31:20.080,0:31:24.880

Siddhartha's uh follow-up is music to my
ears really because one of the things I see

0:31:24.880,0:31:30.320

as a professor of human factors is humans are
fallible and humans are brilliant and our job

0:31:30.320,0:31:35.280

is to design systems that minimize the impact
of human fallibility and maximize the impact of



0:31:35.280,0:31:40.000

human brilliance and what Siddhartha is really talking about is we need to design a resilient

0:31:40.000,0:31:46.960

transport system and we need to remember that very often sources of resilience are human brilliance

0:31:46.960,0:31:53.760

so we're very very good at noting when things go wrong but actually we're not so good at realizing

0:31:53.760,0:31:58.880

the number of times that things go right and Siddhartha's example of the zebra crossing is

0:31:58.880,0:32:03.680

actually it's it's brilliant because think about the subtleties of human behaviour that happen

0:32:03.680,0:32:09.280

as you stop at a zebra crossing um because you stop you observe you don't just observe whether

0:32:09.280,0:32:13.920

there's a person and whether they're walking across the zebra crossing you observe the age

0:32:13.920,0:32:18.480

of that person you observe whether they've got



mobility impairments of some sort and they might

0:32:18.480,0:32:24.400

need to um uh walk more slowly you might even have
a little friendly wave or a smile at the person i

0:32:24.400,0:32:29.840

live in Nottingham so we're very friendly here um
and uh or you might have someone who's standing

0:32:29.840,0:32:33.760

at the side of the road they realize oh whoops
I've stood by the side the road I'm on my phone

0:32:33.760,0:32:39.440

they'll give a little wave to the driver and we're
talking about what five ten seconds of interaction

0:32:39.440,0:32:45.120

here the complexity of programming all of those
different possibilities is absolutely enormous

0:32:45.120,0:32:50.720

but also let's remember that humans are
sentient beings and actually it's quite nice

0:32:50.720,0:32:55.280

if you're driving along and you stop and you have
a pleasant interchange with a passenger um sorry



0:32:55.280,0:33:02.160

with a pedestrian on a zebra crossing um so just thinking about where the economies of scale are

0:33:02.160,0:33:08.480

in introducing automation um is really really important and and this comes back to the fact

0:33:08.480,0:33:15.200

that are we really talking about fully autonomous vehicles or are we talking about um vehicles that

0:33:15.200,0:33:20.560

really help you in those situations where we know that human fallibility comes to the fore

0:33:20.560,0:33:25.520

so one of the things that is a human cognitive and physiological limitation is fatigue and

0:33:25.520,0:33:30.960

distraction fatigue and distraction comes much more into play when we're on motorway driving

0:33:30.960,0:33:34.800

so the case for autonomous vehicles in a motorway setting

0:33:34.800,0:33:40.480

is much stronger than in that sort of city



or town type environment where not only is

0:33:40.480,0:33:45.760

it much more complex to design autonomy but actually also humans are often brilliant.

0:33:46.880,0:33:51.760

Mohammed.

Yeah so I want to emphasize the importance of

0:33:51.760,0:33:57.840

trust in all these scenarios right so we tend to trust uh the system then we think it's helpful to

0:33:57.840,0:34:01.840

us and then the scenarios that Sarah pointed out are those scenarios where autonomous systems are

0:34:01.840,0:34:07.360

likely to be much more helpful than in an urban situation in London when there are lots of uh

0:34:08.080,0:34:12.800

different sorts of road users that that may interfere with what the autonomous system will

0:34:12.800,0:34:20.160

want to do so you think that trust level is is something that we need to be able to measure and



0:34:20.160,0:34:26.960

understand properly by looking at human aspects
of autonomous driving and also we should find

0:34:26.960,0:34:32.400

the right compromise between things like safety
comfort of the the human driver all those aspects

0:34:32.400,0:34:37.840

will play into the measurable notion of trust that
you are going to develop in in the coming years.

0:34:37.840,0:34:40.560

How's the TAS Hub going to help
with some of these problems then?

0:34:40.560,0:34:43.920

One of the great things about the
Trustworthy Autonomous Systems Hub

0:34:43.920,0:34:47.840

is the fact that it's bringing people together
from all sorts of different perspectives

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one of the things that that's particularly
helpful is that we've got a really strong

0:34:53.360,0:34:58.880

multi-disciplinary perspective so we're not just



looking at the engineering solution in isolation

0:34:58.880,0:35:03.840

we're not just looking at the computer science
solution in isolation we've got social scientists

0:35:03.840,0:35:09.040

we've got legal experts we've got um engineers
we've got computer scientists we've got designers

0:35:09.040,0:35:13.520

who are all working together on some of these
wicked problems that we're encountering when

0:35:13.520,0:35:17.920

it comes to the trustworthy autonomous systems
the other thing though is that the Trustworthy

0:35:17.920,0:35:24.800

Autonomous Systems Hub with with association with
the Nodes also has a mission to influence policy

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um and to accelerate the um embedding of the novel
technologies in an industrial and a policy setting

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so I think that in many ways it's worth thinking
of the TAS Hub as being a convener of all of these



0:35:39.680,0:35:44.160

different perspectives and transfer of knowledge
between different settings we've talked quite a

0:35:44.160,0:35:49.280

lot about transport today but there are other
sectors particularly manufacturing for example

0:35:49.280,0:35:55.920

where we see a lot of the autonomous technologies
being used and being able to learn from one sector

0:35:55.920,0:35:59.360

and apply it to another sector is something
else I think that the TAS Hub really brings

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Mohammed.

0:36:01.680,0:36:07.040

And so I think one other aspect that the TAS
Programme uh could be very very helpful in is

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building a community around the trustworthy
autonomous system and raising awareness both

0:36:11.440,0:36:16.640

in terms of policy making it but also in terms of
interaction and engagement with the general public



0:36:17.200,0:36:22.320

and that's something that has already started so
we see Pump Priming for our projects that that

0:36:22.320,0:36:26.080

involve institutions that are
not traditionally part of the

0:36:26.080,0:36:31.920

TAS Programme uh interacting with the TAS Hub and
the Nodes and I think this is something that will

0:36:31.920,0:36:39.040

sustain for a few years and then they'll have
a very uh wide and large and broad community of

0:36:39.040,0:36:41.360

different stakeholders engaging
with the TAS Programme which is

0:36:41.360,0:36:45.840

fascinating I don't think this has this has
happened anywhere else in the world so far.

0:36:46.800,0:36:51.760

Joe.

I'm involved in a Pump Priming project um which

0:36:51.760,0:37:00.160



is investigating the use of um the use of data
in autonomous vehicles and the user's ability and

0:37:01.280,0:37:04.800

the ethical and legal implications
of the recording of that data

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and certainly having um and as Sarah's pointed
out having a this multi-disciplinary team

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um but having having a legal background and
then being able to work on this project with a

0:37:17.440,0:37:25.760

multi-disciplinary team um has provided
a fantastic platform for me personally

0:37:26.880,0:37:33.200

to be able to think about these ideas in in a
completely different way um where for example

0:37:33.200,0:37:39.680

where we're um we're putting our ideas in
terms of where we're building simulations

0:37:41.600,0:37:48.160

of of autonomous vehicle scenarios and and how
being able to provide input into the types of



0:37:48.160,0:37:54.880

scenarios that we think may occur in a day in a day-to-day um situation and the types of data that

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that needs to be recorded and how that data can be used and and being able to have this tackled from

0:38:01.200,0:38:08.880

all different sciences I think it's going to be um very useful and it is going to end up with the

0:38:08.880,0:38:13.200

types of conclusions that we're going to be able to draw um and the recommendations that we're

0:38:13.200,0:38:19.760

going to make are going to be that much stronger um so I'm very excited to be involved in this.

0:38:22.280,0:38:23.280

Siddhartha.

0:38:23.280,0:38:26.880

I think a lot has been said but one thing I would like to say is

0:38:26.880,0:38:33.680

uh not only the multi-disciplinarity of of the



Hub but also learning from different domains

0:38:33.680,0:38:39.600

so we've talked a lot about road autonomous vehicles right now but aviation has had on

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automation for a long long time a lot of good things about that that we can learn from,

0:38:45.040,0:38:50.560

marine has is also introducing on automation right now uh sarah mentioned about manufacturing

0:38:50.560,0:38:53.920

automation so there are a lot of things that we can learn from other industries

0:38:53.920,0:39:00.240

especially into the road and land domain and I think such a programme enables that to happen

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so I think that that's a very uh important aspect that we shouldn't forget that uh we are good at

0:39:05.440,0:39:10.560

what we are doing in our domain but there's other brilliant engineers also working in other domains.



0:39:11.120,0:39:16.960

Space of course but yes the first word came
from Jack maybe i'll give you the last word Jack

0:39:16.960,0:39:22.640

The difficult thing the big challenge faced
by engineers working on questions of of

0:39:22.640,0:39:29.680

trustworthiness and by the Trustworthy Autonomous
Systems Hub in in particular is that ultimately

0:39:29.680,0:39:35.040

you know we people in universities we researchers
designers of technology we don't get to decide

0:39:35.760,0:39:41.200

what gets trusted right that's for that's
for society it's ultimately a democratic

0:39:41.920,0:39:46.640

question and ultimately the things
that determine trustworthiness

0:39:47.200,0:39:52.800

are not just whether a system does what we expect
it to do right which are the sort of things that

0:39:52.800,0:39:59.680

engineers can check and certify and assure and all



the rest of it but often people are interested in

0:39:59.680,0:40:05.120

how systems function so opening up the black
box of technology and they're interested in what

0:40:05.120,0:40:10.400

systems are for as well so they're interested in
the purposes of technology and the trustworthiness

0:40:10.400,0:40:18.160

of these systems might be undermined by for
example um their use in cutting people's jobs

0:40:18.160,0:40:23.840

or their use in you know enabling rich people
to get about but doing nothing for poor people

0:40:24.640,0:40:31.840

so those questions trust is re is a really
complicated multi-dimensional uh issue

0:40:31.840,0:40:38.400

and it means that it's hard for engineers to
end the conversation right what they can do is

0:40:38.400,0:40:42.800

help to start the conversation and inform
it but ultimately it becomes a democratic



0:40:42.800,0:40:48.320

challenge which makes it very tricky and extremely interesting if you're a social scientist like me.

0:40:48.320,0:40:52.400

So you're you're off to do a very big new job which we'll be doing by the time people watch

0:40:52.400,0:40:58.080

this and what do you think about the TAS Hub so as incoming chief scientific advisor for the

0:40:58.080,0:41:02.560

department for transport I'm absolutely delighted that the Trustworthy Autonomous Systems Hub

0:41:02.560,0:41:09.600

and its Nodes are in place one of the things that will be my job is making sure that I've got access

0:41:09.600,0:41:14.800

to an understanding of the excellent science and social science and engineering research that's

0:41:14.800,0:41:21.920

happening in the UK and that we can smooth the path between that research and its implications

0:41:21.920,0:41:27.520

for policy and for future investment as well



so I'm really really pleased to be able to be

0:41:27.520,0:41:32.480

working with the TAS Hub in my new role as well
as remaining as an investigator on the TAS Hub

0:41:33.120,0:41:35.840

in the current role that I retain
at the University of Nottingham.

0:41:35.840,0:41:40.880

It just remains for me to say thank you
to all of our fireside chat uh chattees

0:41:40.880,0:41:44.160

Sarah Sharples Siddhartha
Khastgir, Mohammad Mousavi,

0:41:44.800,0:41:49.760

Joe Pattinson and Jack Stilgoe. Thank you ever
so much for being part of this for any of more

0:41:49.760,0:41:56.320

information uh you can visit our website tas.ac.uk
where you'll find links to the podcast Living with

0:41:56.320,0:42:07.520

AI details of events news and opportunities and
all the other fireside chats that we'll be doing

Transcript ends



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Autonomous
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